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A new method to compute Mathieu functions

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Abstract. We propose to evaluate the Mathieu functions by their modulus and phase. The modulus is independent of the characteristic exponent. In our approach, this exponent can be evaluated by integration of a first-order differential equation. For the Hamiltonian of the time-dependent harmonic oscillator, we do not need this exponent, only the modulus.

1. Introduction: the former method

The time-dependent harmonic oscillator can be described by Mathieu's differential equation [1–4]

$$\ddot{x} + f(t)x = 0 \quad \text{with} \quad f(t) = f(t - T) = \left(\frac{1}{2}\Omega\right)^2(a - 2q \cos \Omega t). \quad (1)$$

The physical parameters Ω , a and q are given†: all three are real, $\Omega > 0$ and $q > 0$ (otherwise we move the time origin by $\frac{1}{2}T = \pi/\Omega$). The parameter a may be negative; however, then the solutions with $q = 0$ are not stable‡. The possible instability for $q > 0$ will be discussed.

For $q > 0$, we can write down the linear independent *Floquet* solutions in the form§

$$x_{\pm}(t) = \sum_{n=-\infty}^{\infty} C_n \exp\left(\pm i \frac{2n + \nu}{2} \Omega t\right) \quad (2)$$

with real coefficients C_n . Here ν is the *characteristic exponent*: it is real but is not an integer if the solutions are stable||. From Mathieu's differential equation (1), we obtain the recurrence relation

$$C_{n-1} + C_{n+1} = \frac{a - (2n + \nu)^2}{q} C_n. \quad (3)$$

† We are looking here for the solutions of the *initial-value problem* and defer the discussion of the related *boundary-value problem* with purely periodic solutions to section 3: that problem is solved by an infinite system of characteristic values $a_n(q)$.

‡ i.e. linear combinations of $x_{\pm}(t) = \exp(\pm i \frac{1}{2} \sqrt{a} \Omega t)$.

§ Blanch [4] writes c_{2n} instead of C_n .

|| For unstable solutions, ν becomes complex with an integer real part.

Setting $G_{\pm n} \equiv C_{\pm n}/C_{\pm(n-1)}$ for $n \geq 0$ and using $\lim_{n \rightarrow \infty} G_{\pm n} \rightarrow 0$ gives

$$G_{\pm n} = \frac{q}{a - (2n \pm \nu)^2 - qG_{\pm(n+1)}}. \tag{4}$$

The characteristic value ν must be chosen such that (3) has a non-trivial solution† or, equivalently, $G_0G_{-1} = 1$. (We may take $\nu > 0$ for stable solutions and $\text{Im } \nu > 0$ for unstable solutions, otherwise we have to interchange x_+ and x_- .)

From the set $\{G_n\}$, we obtain all C_n except C_0 which is determined by $x_{\pm}(0) = 1$, i.e. $\sum_n C_n = 1$ or

$$C_0^{-1} = 1 + G_1(1 + G_2(1 + \dots)) + G_{-1}(1 + G_{-2}(1 + \dots)). \tag{5}$$

In this normal procedure, we first have to compute ν to obtain the Floquet solutions. As

$$x_{\pm}(t + T) = \exp(\pm i\nu\pi)x_{\pm}(t) \tag{6}$$

this quantity has a physical meaning apart from the factor π : for stable solutions it is the phase shift‡ picked up during the period T . This quasiperiodicity is characteristic of Floquet's solutions x_{\pm} . Another *fundamental system* x_1 and x_2 can be determined by the initial values $x_1(0) = 1 = \dot{x}_2(0)$ and $\dot{x}_1(0) = 0 = x_2(0)$.

2. A new method

By introducing the modulus and phase of the Floquet solutions (see [5] or [6])

$$x_{\pm}(t) = \alpha(t) \exp\{\pm i\varphi(t)\} \tag{7}$$

we obtain two differential equations with a constant w §.

$$\dot{\varphi} = \frac{w}{\alpha^2} \quad \text{and} \quad \ddot{\alpha} + f\alpha = \frac{w^2}{\alpha^3}. \tag{8}$$

Apart from the factor $\exp(\pm \frac{1}{2}i\nu\Omega t)$, the solutions x_{\pm} must be periodic. This leads to $\alpha(t + T) = \alpha(t)$ and $\varphi(t + T) = \varphi(t) + \nu\pi$.

The constant w must be chosen properly—otherwise we would not have the correct periodicity of the modulus—and depends on the initial values. Choosing $x_{\pm} = x_1 \pm iw x_2$, we have $\alpha(0) = 1$, $\dot{\alpha}(0) = 0$ and $\varphi(0) = 0$ besides $\dot{\varphi}(0) = w$. Since $\nu > 0$, we have $w > 0$ and w is then the *Wronskian* $w = (\dot{x}_+x_- - x_+\dot{x}_-)/(2i)$. Since $\dot{\alpha}(0) = 0$, we obtain $\alpha(t)$ as an even function in t , simplifying our procedure.

† After Hill (see e.g.[3] p 124), this gives the condition $\sin^2 \frac{1}{2}\pi\nu = \Delta \sin^2 \frac{1}{2}\pi\sqrt{a}$ where Δ is the determinant of an infinite tridiagonal matrix with 1 as its diagonal elements and $q/(4n^2 - a)$ as the neighbours of these elements. For high precision we have to use a high-dimensional matrix because of the slow convergence of Δ .

‡ For unstable solutions, ν characterizes the instability.

§ This follows from the integration of $\alpha\ddot{\varphi} + 2\dot{\alpha}\dot{\varphi} = 0$. For unstable solutions, we set $x_{\pm}(t) = \alpha(t) \exp\{\pm i\varphi(t)\}$ and get $\ddot{\alpha} + f\alpha = -w^2/\alpha^3$ while the differential equation for φ remains unchanged. Thus, we can use all equations for unstable solutions α as well by substituting w^2 by $-w^2$.

Evidently, we first need a solution of the inhomogeneous and nonlinear differential equation for $\alpha(t)$. Afterwards, we can determine the phase $\varphi(t)$ —and the characteristic exponent $\nu = \varphi(T)/\pi$ —from a differential equation of *first order*.

Actually, we work with

$$y = \alpha^2 \quad \text{as function of } \tau = \Omega t \tag{9}$$

instead of α . Indicating differentiation with respect to τ by a prime, we obtain the nonlinear inhomogeneous differential equation

$$yy'' - \frac{1}{2}y'^2 + 2\Omega^{-2}fy^2 = 2\Omega^{-2}w^2 \tag{10}$$

with $2\Omega^{-2}f = \frac{1}{2}(a - 2q \cos \tau)$. Since y is even and periodic like α , we have the even Fourier expansion†

$$y = \sum_{n=0}^{\infty} b_n \cos n\tau \tag{11}$$

and we insert this into the differential equation (10). Comparing the time-independent terms, we find

$$\left(\frac{2w}{\Omega}\right)^2 = \sum_{n=0}^{\infty} (1 + \delta_{n0}) \left(\frac{a - 3n^2}{2} b_n^2 - q b_n b_{n+1}\right). \tag{12}$$

The terms connected with $\cos n\tau$ for $n \in \{1, 2, \dots\}$ yield a bilinear system of equations

$$\begin{aligned} &\sum_{k=0}^n \frac{[a - (n - k)^2](n - k) + [a - k^2]k}{2n} b_k b_{n-k} \\ &\quad + \sum_{k=0}^{\infty} \frac{[a - (n + k)^2](n + k) - [a - k^2]k}{n} b_k b_{n+k} \\ &= q \frac{b_1 b_n + b_0 b_{n+1} + b_0^2 \delta_{n1}}{2} + q \sum_{k=0}^{n-1} b_k \frac{b_{n-k-1} + b_{n-k+1}}{2} \\ &\quad + q \sum_{k=0}^{\infty} b_k (b_{n+k-1} + b_{n+k+1}) \end{aligned}$$

that can be solved by the recurrence relation

$$\frac{2n - 1}{2n - \delta_{n1}} b_{n-1} + \frac{2n + 1}{2n} b_{n+1} = \frac{a - n^2}{q} b_n. \tag{13}$$

This relation may be compared with (3) giving the usual coefficients C_n : we do not need the characteristic exponent ν and have only positive indices n .

In order to keep rounding errors small, it is advisable to calculate, as a first step, the ratio $g_n \equiv b_n/b_{n-1}$ from the recurrence relation

$$g_n = \frac{2n - 1}{2n - \delta_{n1}} \frac{q}{a - n^2 - (1 + \frac{1}{2}/n)qg_{n+1}}. \tag{14}$$

† For an unstable solution, we have to substitute $\cos n\tau$ by $\cosh n\tau$.

Table 1. Fourier coefficients b_n for two examples with $a = 0$ (one in the stable region ($q = \frac{1}{2}$) and one at the boundary ($q \approx 0, 9$)) and the example $a = 3, q = \frac{1}{2}$ (in the stable region).

n	$a = 0$ $q = 0, 5000$	$a = 0$ $q = 0, 9080$	$a = 3$ $q = 0, 5000$
0	$2, 0 \times 10^{+00}$	$1, 3 \times 10^{+04}$	$8, 8 \times 10^{-01}$
1	$-1, 1 \times 10^{+00}$	$-1, 6 \times 10^{+04}$	$1, 9 \times 10^{-01}$
2	$1, 0 \times 10^{-01}$	$2, 8 \times 10^{+03}$	$-7, 5 \times 10^{-02}$
3	$-4, 6 \times 10^{-03}$	$-2, 4 \times 10^{+02}$	$5, 2 \times 10^{-03}$
4	$1, 3 \times 10^{-04}$	$1, 2 \times 10^{+01}$	$-1, 8 \times 10^{-04}$
5	$-2, 3 \times 10^{-06}$	$-3, 9 \times 10^{-01}$	$3, 6 \times 10^{-06}$
6	$2, 9 \times 10^{-08}$	$8, 9 \times 10^{-03}$	$-5, 0 \times 10^{-08}$
7	$-2, 7 \times 10^{-10}$	$-1, 5 \times 10^{-04}$	$5, 1 \times 10^{-10}$
8	$2, 0 \times 10^{-12}$	$2, 0 \times 10^{-06}$	$-3, 9 \times 10^{-12}$
9	$-1, 2 \times 10^{-14}$	$-2, 2 \times 10^{-08}$	$2, 4 \times 10^{-14}$
10	$5, 6 \times 10^{-17}$	$1, 9 \times 10^{-10}$	$-1, 2 \times 10^{-16}$

This is as in the usual numerical calculation. For high n we can ignore g_{n+1} compared to $n^2 - a$ as well and thus, can find all g_n up to $n = 1$. Subsequently, we can determine b_0 from $\alpha(0) = 1$ or $y(0) = \sum_{n=0}^{\infty} b_n = 1$ to get

$$b_0^{-1} = 1 + g_1(1 + g_2(1 + \dots)) \quad (15)$$

and then all b_n from $b_n = g_n b_{n-1}$.

Equation (12) can be converted by the recurrence relation into the fast converging series

$$\left(\frac{2w}{\Omega}\right)^2 = a \left(b_0^2 - \sum_{n=1}^{\infty} b_n^2\right) + q \left(2 \sum_{n=1}^{\infty} b_n b_{n+1} - \frac{1}{2} b_0 b_1 + \frac{3}{4} \sum_{n=1}^{\infty} \frac{b_n b_{n+1}}{n(n+1)}\right). \quad (16)$$

(For unstable solutions we get a factor -1 as mentioned in footnote § on page 5566.)

From (8), we get the phase

$$\varphi(t) = \frac{w}{\Omega} \int_0^{\Omega t} \frac{d\tau}{\sum_{n=0}^{\infty} b_n \cos n\tau}. \quad (17)$$

As a consequence of the even Fourier series, we have $y(\tau) = y(2\pi - \tau)$ and thus, can restrict ourselves to $0 \leq \Omega t \leq \pi$, obtaining the characteristic exponent from

$$\nu = \frac{2}{\pi} \varphi\left(\frac{1}{2} T\right). \quad (18)$$

The integrals can be calculated numerically by Simpson's method. (Using intervals of equal length has advantages when computing Fourier series: we should compute the often used cosines at $2\pi/(2N)$ once and store them. This is more profitable than the Gauss-Legendre method.)

3. Discussion

The Fourier series $\sum_n b_n \cos n\tau$ converges very fast because the coefficients b_n get smaller, nearly as $q^n/(n!)^2$, with increasing n as a result of the recurrence relation. The convergence is also shown in table 1. Besides avoiding the parameter ν , we also have only positive n .

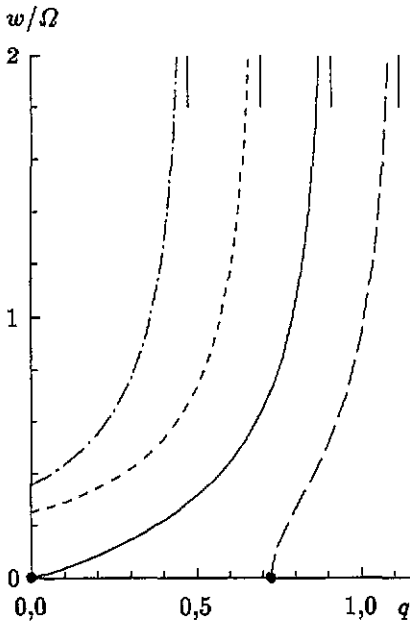


Figure 1. Wronskian w divided by driving frequency Ω as a function of q ; shown for $a = -\frac{1}{4}$ (long broken curve), $a = 0$ (full curve), $a = \frac{1}{4}$ (broken curve) and $a = \frac{1}{2}$ (chain curve). Vertical lines and bullets mark the boundary of stability.

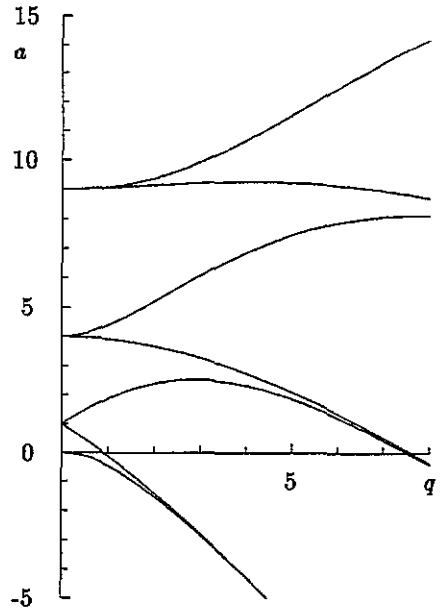


Figure 2. Stability chart for the Mathieu functions with $0 \leq q \leq 8$ and $-5 \leq a \leq 15$ as derived from (12). The curves display the boundaries, which apparently increasingly restrict the stable regions with growing q .

The Wronskian w is determined by the fundamental solutions x_{\pm} and can be calculated from (16) as a function of parameters a and q (without using the characteristic exponent). Figure 1 displays $w(q)/\Omega$ for some parameters a .

At the boundary of stability, the Wronskian diverges (or vanishes). Even this boundary can be determined without the use of ν : we only need to find the change of sign in (16) as a function of a and q . The result is plotted in figure 2 for $0 \leq q \leq 8$ and $-5 \leq a \leq 15$.

Applications [1, 2] often need periodic Mathieu functions with integer values of ν . This *boundary problem* can be solved only for special characteristic values a_{ν} with integer ν . At these values of a , the solutions change from stable to unstable and can thus be found from the stability chart (figure 2).

In figure 3, we show α and φ as functions of t/T in the interval of periodicity $[0, 1]$ for $a = 0$ and several values of q . In figure 4, we display the respective functions $\alpha \cos \varphi$ for the larger interval $0 \leq t/T \leq 8$ since the periodicity cannot be seen as well.

The decomposition in modulus and phase is useful for physical applications too: according to Brown [5], the Hamiltonian of the time-dependent oscillator

$$H = \frac{p^2}{2m} + \frac{m}{2} f(t)x^2 \tag{19}$$

can be transformed with the generating function $G(t, p, x') = -\alpha(px' - \frac{1}{2}m\dot{\alpha}x'^2)$, i.e. by $x = -\partial G/\partial p = \alpha x'$ and $p' = -\partial G/\partial x' = \alpha(p - m\dot{\alpha}x')$ into the form

$$H' = \frac{1}{\alpha^2} \left(\frac{p'^2}{2m} + \frac{m}{2} w^2 x'^2 \right). \tag{20}$$

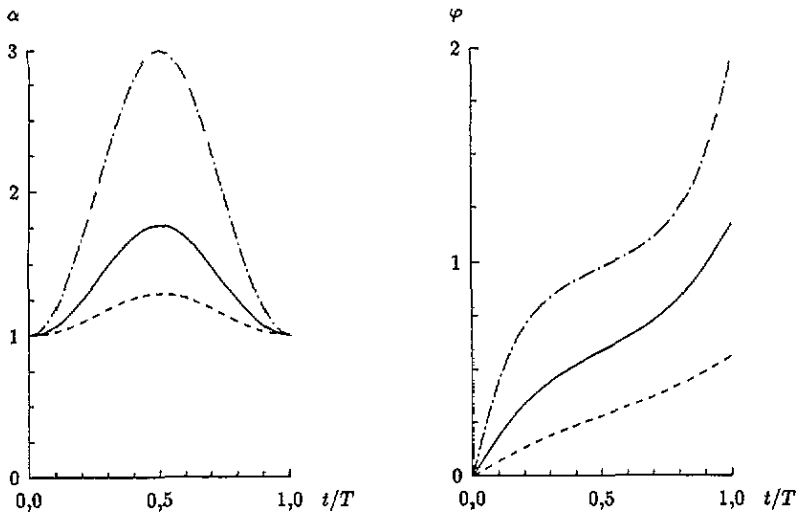


Figure 3. Modulus α and phase φ of the Mathieu functions with $a = 0$ as functions of t/T ; shown for $q = \frac{1}{4}$ (broken curve), $q = \frac{2}{4}$ (full curve) and $q = \frac{3}{4}$ (chain curve).

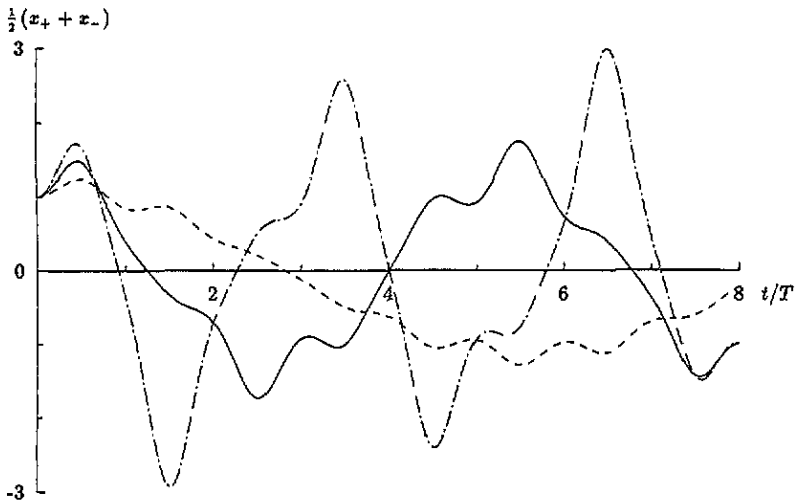


Figure 4. The real part of the Mathieu functions x_{\pm} with the same parameters as in figure 3.

Thus, we need only the modulus of the Mathieu functions and the Wronskian w and can ignore the characteristic exponent ν . Thus, our method is most effective in this case.

In [7], we propose to write

$$H' = \frac{Iw}{\alpha^2} = I\dot{\varphi} \quad (21)$$

with the invariant†

† The connection between $H(t)$ and an invariant divided by a known time-dependent function is already known [8–10].

$$Iw = \frac{p'^2}{2m} + \frac{m}{2}w^2x'^2. \quad (22)$$

That is, I does not depend on time like the Hamiltonian of the time-independent harmonic oscillator of mass m and frequency w . In quantum mechanics, the eigenvalues of I are $(n + \frac{1}{2})\hbar$.

For all observables B , the Hamiltonian H' determines their time dependence by

$$\frac{dB}{dt} = [B, H'] + \frac{\partial B}{\partial t} = \left([B, I] + \frac{\partial B}{\partial \varphi} \right) \frac{d\varphi}{dt}. \quad (23)$$

Thus, it seems to be favourable to take $\varphi(t)$, instead of t , as the independent variable giving

$$\frac{dB}{d\varphi} = [B, I] + \frac{\partial B}{\partial \varphi}. \quad (24)$$

For example, we get $x' = \sqrt{2I/mw} \sin \varphi$ and $p' = \sqrt{2Imw} \cos \varphi$.

In conclusion, the modulus of the Mathieu functions and their Wronskian can be calculated directly without the characteristic exponent with a very effective numerical algorithm. For the Hamiltonian of the time-dependent oscillator and the stability, only the modulus and Wronskian are relevant. With these quantities, we can determine the phase and the characteristic exponent by a differential equation of first order. In this way, Mathieu functions can be calculated more accurately than with the usual methods.

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